

SU²: Advanced Analysis Topics

OpenMDAO-SU² Joint Workshop

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The Open-Source CFD Code

Three Main Topics

- Getting up to speed with SU²
 - Configuring a RANS simulation
- Advanced Analysis Topics
 - Steady flows with moving walls
 - Unsteady flows with fixed geometry
 - Unsteady flows on dynamic meshes
- Getting started with optimal shape design
 - Setting up a 2-D airfoil optimization

Getting up to Speed with SU²



aerospace**design**lab



Getting up to Speed with SU²

vmmetry

The workflow for RANS...

- Prepare geometry & mesh beforehand.
- Choose appropriate physics.
- Set proper conditions for a viscous simulation.
- •Select numerical methods:
 - Convective terms
 - •Viscous terms
 - •Time Integration
 - Multi-grid
- Run the analysis.
- Post-process the results.

% Mesh input file MESH_FILENAME= mesh_ONERAM6_turb_hexa.su2

----- Read grid file information -----Three dimensional problem. 43008 interior elements. 46417 points, and 0 ghost points. 3 surface markers. 2560 boundary elements in index 0 (Marker = FARFIELD). 1408 boundary elements in index 1 (Marker = WING). 2688 boundary elements in index 2 (Marker = SYMMETRY).



Getting up to Speed with SU²

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- a) Store the gas constants and freestream temperature, then calculate the speed of sound.
- b) Calculate and store the freestream velocity from the Mach number & AoA/sideslip angles.
- c) Compute the freestream viscosity from Sutherland's law and the supplied freestream temperature.
- d) Use the definition of the Reynolds number to find the freestream density from the supplied Reynolds information, freestream velocity, and freestream viscosity from step 3.
- e) Calculate the freestream pressure using the perfect gas law with the freestream temperature, specific gas constant, and freestream density from step 4.
- f) Perform any required non-dim.

0 0 oneram6 — vim — 86×47 % Conversion factor for converting the grid to meters CONVERT TO METER= 1.0 % Write a new mesh converted to meters (NO, YES) WRITE_CONVERTED_MESH = NO

Advanced Analysis Topics

- New "Dynamic Mesh" config options
- Unified approach for:
 - Moving walls & rotating frame (steady)
 - Rigidly transforming meshes (unsteady)
 - Dynamically deforming meshes (unsteady)

Moving Walls: Lid-driven Cavity



Moving Walls: Lid-driven Cavity



Erturk, Corke, and Gokcol (2005), "Numerical Solutions of 2-D Steady Incompressible Driven Cavity Flow at High Reynolds Numbers", International Journal for Numerical Methods in Fluids, Vol. 48, pp. 747-774.



- Select MOVING_WALL again
- Input the name of the rotating marker(s), center(s) or rotation, and rotation rate(s)





Moving Walls: Spinning Cylinder



Unsteady RANS: Square Cylinder

0.5

> 0

-0.5

Re = 22,000

Mach = 0.1

- Dual time strategy (1st- or 2nd-order)
- Choose a physical time step using • UNST TIMESTEP
- Set the maximum physical time with ٠ UNST TIME
- UNST INT ITER: maximum number • of pseudo-time steps
- Regular convergence criteria apply for • converging each physical time step



Unsteady RANS: Square Cylinder





Time-averaged C_d = 2.16 agrees well with similar results reported in laccarino, G., et al. "Reynolds averaged simulation of unsteady separated flow." *International Journal of Heat and Fluid Flow* 24.2 (2003): 147-156.

Unsteady Flow: Pitching NACA 64A010

- Set up dual-time strategy as before
- Use RIGID_MOTION option
- Need to give a pitching origin, frequency, amplitude, and possibly phase offset

```
DYNAMIC MESH DEFINITION
% Dynamic mesh simulation (NO, YES)
 GRID MOVEMENT= YES
% Type of mesh motion (NONE, FLUTTER, RIGID_MOTION, FLUID_S)
 GRID_MOVEMENT_KIND= RIGID_MOTION
MACH_MOTION= 0.796
% Coordinates of the rigid motion origin
 OTION ORIGIN X= 0.248
 OTION ORIGIN Y= 0.0
 OTION_ORIGIN_Z= 0.0
% Pitching angular freq. (rad/s) about x, y, & z axes (RIGID_MOTION only)
 ITCHING OMEGA X= 0.0
 ITCHING OMEGA Y= 0.0
 PITCHING_OMEGA_Z= 106.69842
% Pitching amplitude (degrees) about x, y, & z axes (RIGID_MOTION only)
  ITCHING AMPL X= 0.0
  ITCHING AMPL Y= 0.0
  TCHING AMPL Z= 1.01
```





Unsteady Flow: Pitching NACA 64A010



Animation 14



Pitching + Plunging NACA 0012

Z-Vorticity Contours

Plunging is also available... Mach = 0.3, Re = 1000

Animation 15

Getting Started with Shape Design



Shape Optimization is a defining feature of SU²!

- How does one set up an optimization problem?
- How does one use Hicks-Henne bumps?

Shape Design of a Rotating Airfoil





Animation 17



Shape Design of a Rotating Airfoil

The shape design problem...

% Optimization objective function with scaling factor

% ex= Objective * Scale
OPT OBJECTIVE= DRAG * 0.001

% Optimization constraint functions with scaling factors, separated by semicolons SIGN % ex= (Objective = Value) * Scale, use '>','<','=' OPT_CONSTRAINT= NONE

% Optimization design variables, separated by semicolons

(1. 1.0 | airfoil | 0. 0.923076923077); DEFINITION DV= 0.961538461538); 0.807692307692): (1, 1.0 | airfoil | 0, 0.769230769231); (1, 1.0 | airfoil 0. 0.653846153846 0.615384615385 (1. 1.0 | airfoil | 0. 0.576923076923): 0.538461538462); (1, 1.0 | airfoil | 0, 0.230769230769); (1, 1.0 | airfoil | 0, 0.192307692308 0.153846153846 1. 1.0 | airfoil | 0. 0.115384615385); (1, 1.0 | airfoil | 0, 0.0384615384615); (1, 1.0 | airfoil .153846153846 [1. 1.0 | airfoil | 1. 0.192307692308); (1. 1.0 1. 1.0 | airfoil | 1. 0.269230769231): (1. 1.0 | airfoil | 1. 0.307692307692 (1. 1.0 | airfoil | 1. 0.384615384615): 1. 0.346153846154) 0.423076923077); (1, 1.0 | airfoil | 1, 0.461538461538); (1, 1.0 | airfoil 1, 0.538461538462); (1, 1.0 | airfoil | 1, 0.576923076923); (1, 1.0 airfoil | 1. 0.653846153846): 1. 0.884

Hicks-Henne Format: (1, Scale | Mark. List | Lower(0)/Upper(1) side, x_Loc)

Shape Design of a Rotating Airfoil



DEMO